

# On some modern statistical and machine learning approaches for industrial applications

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Talk at:



## The Research and Technology Organisation (RTO) of Paris-Saclay

Research and Technology Organisation (RTO)  
Non-profit Scientific Cooperation Foundation

Paris-Saclay



65

Economic partners  
of which 1/3 are large groups  
and 2/3 are SMEs



50

Academic  
partners

Leads market-driven and applied  
research projects for the digital  
transformation of industry,  
services and territories:

- 1 Expertise: analysis, modeling,  
simulation and decision  
management
- 2 Own skills
- 3 Own assets: software, cyber-  
physical and tool-based  
platforms

5 main application  
domains



Autonomous transport  
and Mobility



Future industry

8 Scientific and technological fields



Data science  
and AI



Interaction  
and uses



Scientific computing



Optimisation



Systems  
engineering



Safety



Digital security  
and blockchain



IoT  
and networks



Defense and Security



Environment and  
Sustainable development



Digital and Health

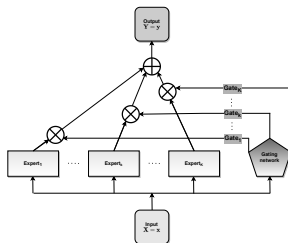
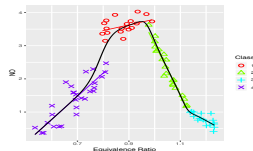
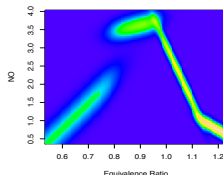
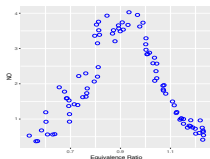
Founding members



- Part 1 : mixtures-of-experts for heterogenous and high-dimensional data
- Part 2 : challenges and industrial applications in Hybrid & Trustworthy AI

# Mixtures-of-Experts to model heterogeneous data

Mixtures-of-Experts as good candidates to model a response  $Y$  given predictors  $X$  governed by a hidden structure accounting for heterogeneity



Schematic diagram of the neural network architecture of a  $K$ -component MoE model.

first studied as neural networks (NNs) by Jacobs, Jordan, Nowlan, and Hinton (1991)  
HD Nguyen and F Chamroukhi. Practical and theoretical aspects of mixture-of-experts modeling : An overview. WIRES : Data Mining and Knowledge Discovery Wiley Periodicals, Inc. 2018



## Density approximation in Unsupervised Learning

- **Data** : observations  $\{\mathbf{x}_i\}$  from  $\mathbf{X} \in \mathbb{X} \subset \mathbb{R}^d$  of density (multimodal)  $f \in \mathcal{F}$
- **Objective** : approximate the density  $f$  (and represent the data, e.g. *clustering*)
- **Solution** : Approximate  $f$  within the class  $\mathcal{H}^\varphi = \bigcup_{K \in \mathbb{N}^*} \mathcal{H}_K^\varphi$  of finite location-scale mixture  $h_K^\varphi$  (of  $K$ -components) of density  $\varphi$  (e.g., Gaussian), where

$$\mathcal{H}_K^\varphi = \left\{ h_K^\varphi(\mathbf{x}) := \sum_{k=1}^K \pi_k \frac{1}{\sigma_k^d} \varphi\left(\frac{\mathbf{x} - \boldsymbol{\mu}_k}{\sigma_k}\right), \boldsymbol{\mu}_k \in \mathbb{R}^d, \sigma_k \in \mathbb{R}_+, \pi_k > 0 \forall k \in [K], \sum_{k=1}^K \pi_k = 1 \right\}$$

## Theorem : Universal approximation of finite location-scale mixtures

- Given any p.d.f  $f, \varphi \in \mathcal{C}$  and a compact set  $\mathbb{X} \subset \mathbb{R}^d$ , there exists a sequence  $(h_K^\varphi) \subset \mathcal{H}^\varphi$ , such that  $\lim_{K \rightarrow \infty} \sup_{\mathbf{x} \in \mathcal{X}} |f(\mathbf{x}) - h_K^\varphi(\mathbf{x})| = 0$ .
- For  $p \in [1, \infty)$ , if  $f \in \mathcal{L}_p$  (Lebesgue p.d.f) and  $\varphi \in \mathcal{L}_\infty$  (essentially bounded p.d.f), there exists a sequence  $(h_K^\varphi) \subset \mathcal{H}^\varphi$ , such that  $\lim_{K \rightarrow \infty} \|f - h_K^\varphi\|_{\mathcal{L}_p} = 0$ .

Nguyen, T., Chamroukhi, F., Nguyen, H. D., & McLachlan, G. J. (2023). Approximation of probability density functions via location-scale finite mixtures in Lebesgue spaces. *Communications in Statistics - Theory and Methods*, 52(14), 5048–5059.  
<https://arxiv.org/pdf/2008.09787>

- **Context** :  $n$  observations  $\{x_i, y_i\}$  from a pair  $(\mathbf{X}, \mathbf{Y}) \in \mathbb{X} \times \mathbb{Y}$  with unknown conditional p.d.f  $f \in \mathcal{F} = \{f : \mathbb{X} \times \mathbb{Y} \rightarrow \mathbb{R}_+ \mid \int_{\mathbb{Y}} f(\mathbf{y}|\mathbf{x}) d\lambda(\mathbf{y}) = 1, \forall \mathbf{x} \in \mathbb{X}\}$
- **High-dimensional setting** :  $\mathbb{X} \subseteq \mathbb{R}^d, \mathbb{Y} \subseteq \mathbb{R}^q$ , with  $d, q \gg n$  and **heterogeneous**.
- **Objectives** : Regression ; Clustering ; Model selection
- **Solution** : Approximate  $f$  within the class of **mixtures-of-experts** :

Let  $\varphi$  be a p.d.f (compactly supported on  $\mathbb{Y} \subseteq \mathbb{R}^q$ ), we define the functional classes :

- Location-scale family :  $\mathcal{E}_\varphi = \left\{ \phi_q(\mathbf{y}; \boldsymbol{\mu}, \sigma) := \frac{1}{\sigma^q} \varphi\left(\frac{\mathbf{y}-\boldsymbol{\mu}}{\sigma}\right); \boldsymbol{\mu} \in \mathbb{Y}, \sigma \in \mathbb{R}_+ \right\}$ .
- Mixture of location-scale experts with softmax activation network : SGaME :

$$\mathcal{H}_S^\varphi = \left\{ h_K^\varphi(\mathbf{y}|\mathbf{x}) := \sum_{k=1}^K g_k(\mathbf{x}; \boldsymbol{\gamma}) \phi_q(\mathbf{y}; \boldsymbol{\mu}_k, \sigma_k); \phi_q \in \mathcal{E}_\varphi \cap \mathcal{L}_\infty, g_k(\cdot; \boldsymbol{\gamma}) \in \{\text{softmax}\} \right\}$$

## Theorem : Approximation capabilities of isotropic mixtures-of-experts SGaME

- For  $p \in [1, \infty)$ ,  $f \in \mathcal{F}_p \cap \mathcal{C}$ ,  $\varphi \in \mathcal{F} \cap \mathcal{C}$ ,  $\mathbb{X} = [0, 1]^d$ , there exists a sequence  $(h_K^\varphi) \subset \mathcal{H}_S^\varphi$  such that  $\lim_{K \rightarrow \infty} \|f - h_K^\varphi\|_{\mathcal{L}_p} = 0$ .
- For  $f \in \mathcal{F} \cap \mathcal{C}$ , if  $\varphi \in \mathcal{F} \cap \mathcal{C}$ ,  $d = 1$ , there exists a sequence  $(h_K^\varphi) \subset \mathcal{H}_S^\varphi$  such that  $\lim_{K \rightarrow \infty} h_K^\varphi = f$  almost uniformly.

Nguyen, H.D., Nguyen, T., Chamroukhi, F., McLachlan G. J. Approximations of conditional probability density functions in Lebesgue spaces via mixture of experts models. Journal of Statistical Distributions and Applications. 8, 13 (2021).

<https://doi.org/10.1186/s40488-021-00125-0>

Learning via the EM algorithm :  $\theta^{new} \in \arg \max_{\theta \in \Omega} \mathbb{E}[\ln L_c(\theta) | \mathcal{D}, \theta^{old}]$

SaMuraiS : open source software for statistical time-series analysis



SaMuraiS : StAtistical Models for the UnsUpervised segmentAtion of time-Series

► [Github](#)

► [CRAN](#)

► [Matlab software](#)

Available algorithms and Packages

RHLP : Regression with Hidden Logistic Process

► [R software](#)

► [Matlab software](#)

HMMR : Hidden Markov Model Regression

► [R software](#)

► [Matlab software](#)

PWR : Piece-Wise Regression

► [R software](#)

► [Matlab software](#)

MRHLP : Multivariate RHLP

► [R software](#)

► [Matlab software](#)

MHMMR : Multivariate HMMR

► [R software](#)

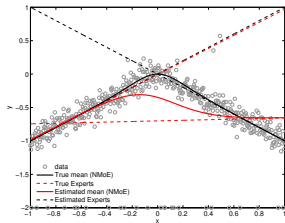
► [Matlab software](#)

MPWR : Multivariate PWR

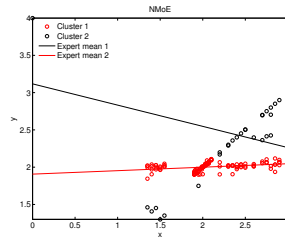
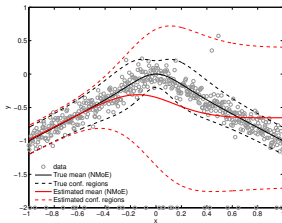
► [R software](#)

► [Matlab software](#)

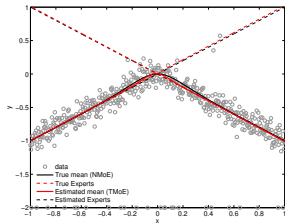
Include estimation, segmentation, approximation, model selection, and sampling



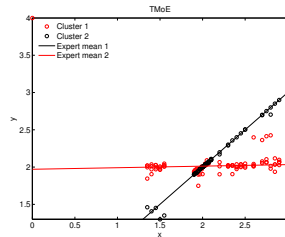
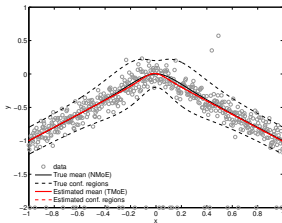
$n = 500$  observations with 5% of outliers ( $x; y = -2$ ) : Normal fit



Tone data with 10 outliers (0, 4) : Normal fit

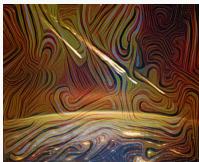


$n = 500$  observations with 5% of outliers ( $x; y = -2$ ) : Robust fit



Tone data with 10 outliers (0, 4) : Robust fit

MEteorits : open-source soft. Robust learning with mixtures-of-experts models



**MEteorits** : Mixtures-of-**Expe**r**T**s mod**EL**ing for c**O**mplex and non-n**O**r**m**al d**IS**tributio**S**

► [Github](#) ► [CRAN](#) ► [Matlab software](#)

## Available algorithms and Packages

N**MoE** : Normal Mixture-of-Experts

► [R software](#)

► [Matlab software](#)

S**NMoE** : Skew-Normal Mixture-of-Experts

► [R software](#)

► [Matlab software](#)

t**MoE** : Robust MoE using the  $t$ -distribution

► [R software](#)

► [Matlab software](#)

S**tMoE** : Skew- $t$  Mixture-of-Experts

► [R software](#)

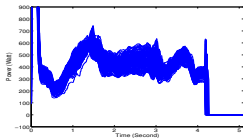
► [Matlab software](#)

- Meteorits include sampling, fitting, prediction, clustering with each MoE model
- Non-normal mixtures (and MoE) is a very recent topic in the field

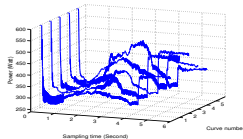
# Some real-world data

- Heterogenous, Multimodal, High-Dimensional, Unlabeled, Possibly Massive ...
- Need for adapted analysis tools

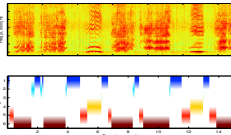
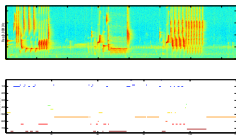
## Transport : Railway switch curves diagnostic



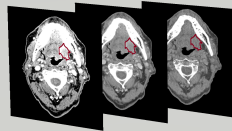
## Predictive Maintenance



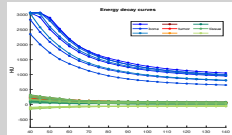
## Acoustics : scene listening (marine, terrestrial)



## Health : Medical images



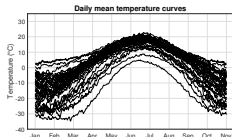
## Dual-energy computed tomography



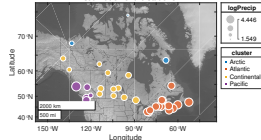
## Health & Well Being : Activity recog.



## Climate/Environment : meteorological data



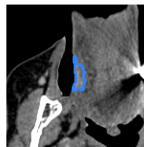
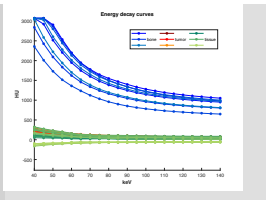
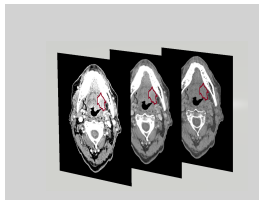
### Visualization of the stations



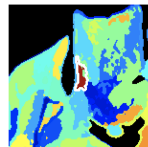
- Learning from Multimodal information in Healthcare/Radiology
- Cancer detection in Radiology : DECT clustering [Diagnostics (AI in medicine), 2022]

Spatial mixture of functional regressions for dual-energy CT images

$$m(\mathbf{y}|\mathbf{x}, \mathbf{v}; \boldsymbol{\theta}) = \sum_{k=1}^K \alpha_k(\mathbf{v}; \boldsymbol{\alpha}) f_k(\mathbf{y}|\mathbf{x}; \boldsymbol{\theta}_k) \text{ where } \alpha_k(\mathbf{v}; \boldsymbol{\alpha}) = \frac{w_k \phi_3(\mathbf{v}; \boldsymbol{\mu}_k, \mathbf{R}_k)}{\sum_{\ell=1}^K w_{\ell} \phi_3(\mathbf{v}; \boldsymbol{\mu}_{\ell}, \mathbf{R}_{\ell})}$$

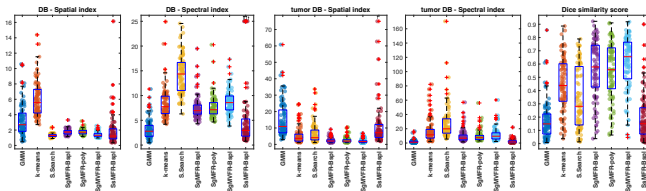


(a) Original slice



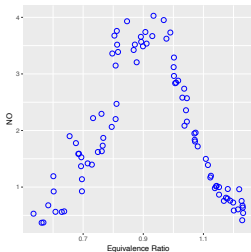
(b) Dice=0.84, DB=1.64/6.92

DECT multimodal Data : 3D voxels & energy levels Expert Annotation Automatic Annotation

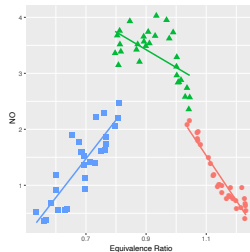
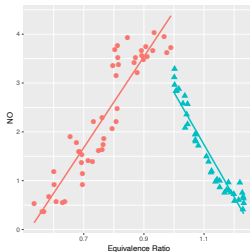


► Codes available on Github

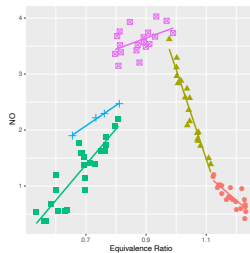
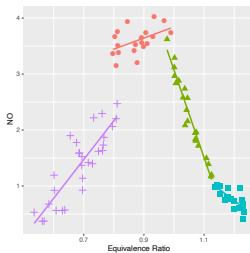
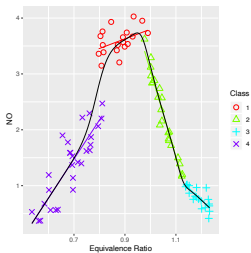
(a) Raw Ethanol data set



Collection of MoE models with linear mean functions characterized by 2-5 clusters



(b) Best data-driven MoE model





**Questioning** : Prediction (non-linear regr., classification) & clustering in presence of

[1.] **High-dimensional** predictors :  $\mathbf{X}_i \in \mathbb{R}^p$  with  $p \gg n$

[2.] **Functional** predictors :  $X_i(t)$ ,  $t \in \mathcal{T} \subseteq \mathbb{R}$  {eg. continuously recorded variables}

↪ Look for parsimonious and interpretable methods

### [1.] HDME : High-Dimensional Mixtures-of-Experts

■ Learning : PMLE  $\hat{\theta}_n \in \arg \max_{\theta} \sum_{i=1}^n \log h_K^{\varphi}(\mathbf{y}_i | \mathbf{x}_i; \theta) - \text{pen}(\theta)$

■ ↪ Lasso penalty :  $\text{Pen}_{\lambda}(\theta) = \underbrace{\sum_{k=1}^K \lambda_k \|\beta_k\|_1}_{\text{Experts Net.}} + \underbrace{\sum_{k=1}^{K-1} \gamma_k \|\mathbf{w}_k\|_1}_{\text{Gating Net.}}$

↪ encourages sparse solutions & performs estimation and feature selection

↪ computationally attractive (Avoid matrix inversion; univariate updates)

▶ **Software Toolbox HDME on Github (GaussRMoE, LogisticRMoE, PoissonRMoE)**

↪ A non-asymptotic result. If  $\text{pen}(\mathbf{m})$  is well chosen, then our PMLE behaves in a comparable manner compared to **the best (oracle) model**  $\mathcal{H}_{\mathbf{m}^*}$  in the collection

Nguyen TT, Nguyen HD, Chamroukhi F and Forbes F. A non-asymptotic approach for model selection via penalization in high-dimensional mixture of experts models. Electronic Journal of Statistics. 2022

C & Huynh. Regularized Maximum Likelihood Estimation and Feature Selection in Mixtures-of-Experts Models. Journal de la Société Française de Statistique, Vol. 160(1), pp :57–85, 2019

Huynh & C. Estimation and Feature Selection in Mixtures of Generalized Linear Experts Models. arXiv :1810.12161

## [2.] Learning with functional predictors

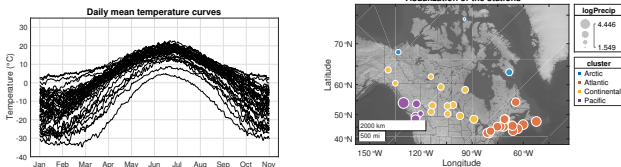


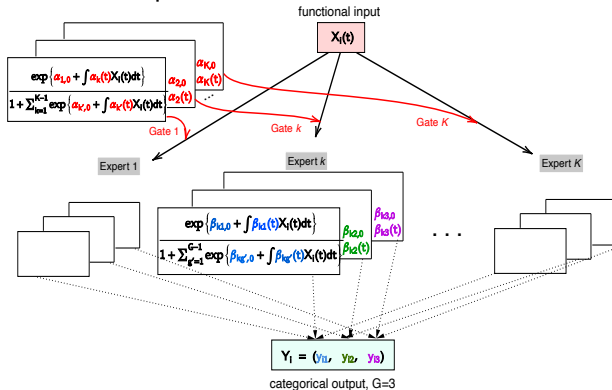
FIGURE –  $n = 35$  **daily mean temperature measurement curves** ( $X_i$ 's) in **different stations** (Left) and the log of precipitation values ( $Y_i$ 's) visualized with the climate regions ( $Z_i$ 's) (Right).

- Relate functional predictors  $\{X(t) \in \mathbb{R}; t \in \mathcal{T} \subset \mathbb{R}\}$  to a scalar response  $Y \in \mathcal{Y} \subset \mathbb{R}$
- Regression and classification of **heterogeneous responses** given **functional predictors**
  - (1) generative functional modeling, sparsity and feature selection (high-dimension)
  - (2) User guideline : keep an interpretable fit

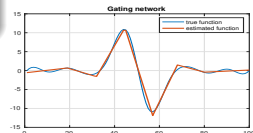
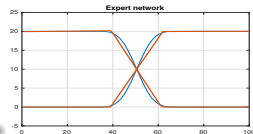
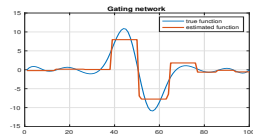
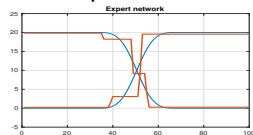
### [2.] Functional Mixtures-of-Experts (and Different Learning strategies, in particular)

- $Y_i = \beta_{z_i,0} + \int_{\mathcal{T}} X_i(t) \beta_{z_i}(t) dt + \varepsilon_i$  avec  $h_{z_i}(X_i(\cdot)) = \alpha_{z_i,0} + \int_{\mathcal{T}} X_i(t) \alpha_{z_i}(t) dt$
- Lasso-type Regularized MLE w.r.t the derivatives of the  $\alpha(\cdot)$  and  $\beta(\cdot)$  functions

## Mixture-of-Experts Architecture



## Interpretable fits



$Y_i = \beta_{z_i,0} + \int_{\mathcal{T}} X_i(t) \beta_{z_i}(t) dt + \varepsilon_i$  with  $h_z(X_i) = \alpha_{z_i,0} + \int_{\mathcal{T}} X_i(t) \alpha_{z_i}(t) dt$   
 $l_1$ -Regularized MLE w.r.t the derivatives of the  $\alpha(\cdot)$  and  $\beta(\cdot)$  functions

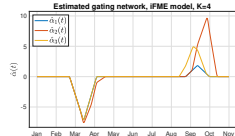
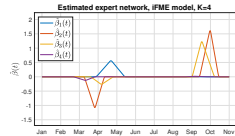
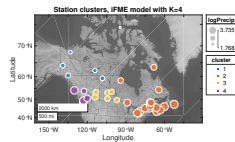
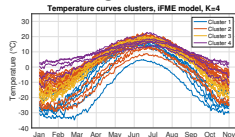
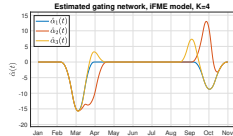
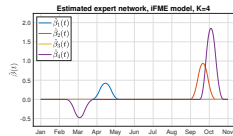
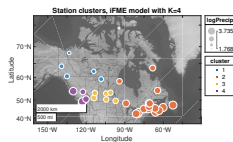
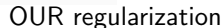
→ produces a meaningful sparse estimates for  $\beta_{z_i}(t)$  curves :

$\beta_{z_i}^{(0)}(t) = 0$  implies that  $X(t)$  has no effect on  $Y$  at  $t$

$\beta_{z_i}^{(1)}(t) = 0$  means that  $\beta_{z_i}(t)$  is constant at  $t$ ,

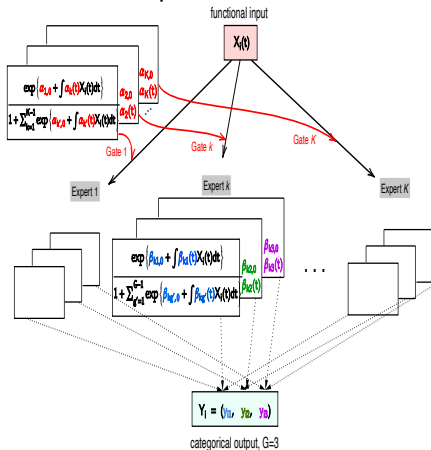
$\beta_{z_i}^{(0)}(t) = 1$  shows that  $\beta_{z_i}(t)$  is a linear function of  $t$ , etc.

## OUR regularization

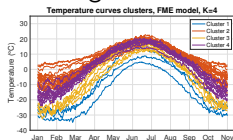


C, Pham, Hoang, McLachlan. Functional Mixtures-of-Experts. *Statistics and Computing* ., Vol. 34 (98), 2024 [open access]

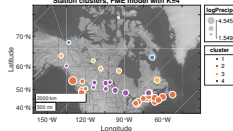
## Mixture-of-Experts Architecture



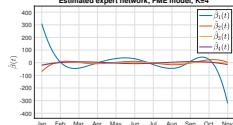
### No regularization



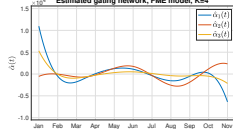
Station clusters, FME model with K=4



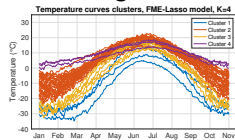
Estimated expert network, FME model, K=4



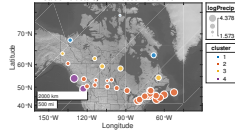
Estimated gating network, FME model, K=4



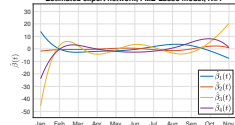
### LASSO regularization



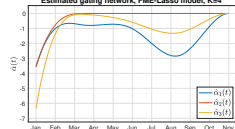
Station clusters, FME-Lasso model with K=4



Estimated expert network, FME-Lasso model, K=4

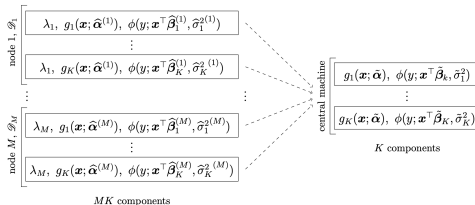


Estimated gating network, FME-Lasso model, K=4



## Aggregating distributed mixtures-of-experts models (MoE)

- collaborative MoE for distributed (eg. large-scale data) or federated learning



- Local estimators :  $\hat{f}_m = f(\cdot | \mathbf{x}, \hat{\boldsymbol{\theta}}_m) = \sum_{k=1}^K g_k(\mathbf{x}, \hat{\boldsymbol{\alpha}}^{(m)}) \phi(\cdot; \mathbf{x}^\top \hat{\boldsymbol{\beta}}_k^{(m)}, \hat{\sigma}_k^{2(m)})$ ,
- weighted average :  $\bar{f} = f(y | \mathbf{x}; \bar{\boldsymbol{\theta}}) = \sum_{m=1}^M \lambda_m \hat{f}_m$  where  $\lambda_m = \frac{N_m}{N}$  the sample proportion.  $\bar{f}$  is good but relates  $MK$  components so not our direct target.
- ↪ Reduced estimator :  $\bar{f}^R = \arg \inf_{h_K \in \mathcal{M}_K} \rho \left( h_K, \sum_{m=1}^M \lambda_m \hat{f}_m \right)$  : we seek for a  $K$ -component ME  $h$  that is closest to the  $MK$ -component ME  $\bar{f} = \sum_{m=1}^M \lambda_m \hat{f}_m$  w.r.t a transportation divergence  $\rho(\cdot, \cdot)$ , e.g. KL.

C and Pham T. Distributed Learning of Mixtures of Experts. *arxiv 2312.09877*, 2024 [under revision at IEEE TNNLS] {PhD, Pham. 2022}

► Source codes publicly available on Github.

## Numerical results in Distributed clustering and Prediction

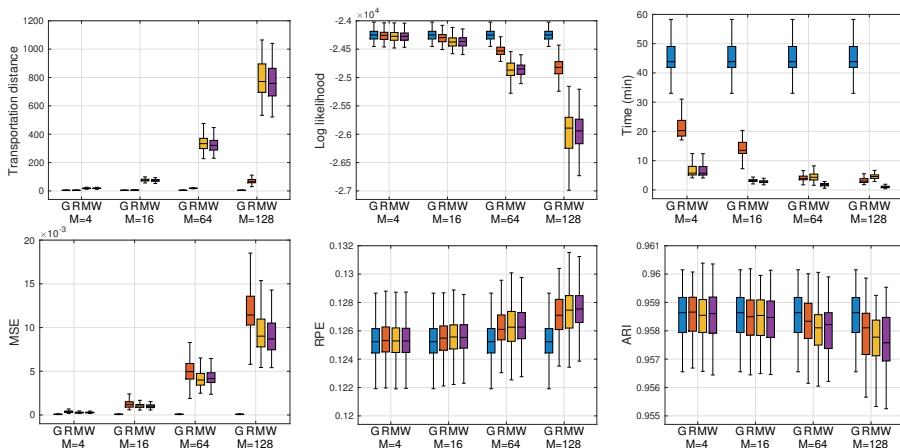


FIGURE – Performance of the Global ME (G), Reduction (R), Middle (M) and Weighted average (W) estimator for sample size  $N = 10^6$  and  $M$  machines.

C and Pham T. Distributed Learning of Mixtures of Experts. *arxiv 2312.09877*, 2024 [under revision at IEEE TNNLS] {PhD, Pham. 2022}

► Source codes publicly available on [Github](#).

# Challenges and industrial applications in Hybrid AI Trustworthy AI

Faïcel Chamroukhi





## Challenges and industrial applications in

- **Hybrid AI:** exploiter les connaissances métiers de natures physique et symbolique dans les modèles d'apprentissage
- **Trustworthy AI:** concevoir et industrialiser des systèmes à base d'intelligence artificielle de confiance

# The Research Program IA2: AI and Augmented Engineering



Intelligence  
artificielle  
et ingénierie  
augmentée

Artificial Intelligence  
an Augmented Engineering

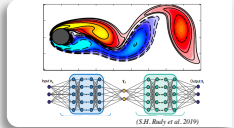
- a program with **6 R&D collaborative projects** based on concrete **industrial use cases**
- Area: Hybrid AI
- 20+ industrial and academic partners

Advance project  
Thesis / Postdocs / Shared work

## HSA: Simulation/machine learning hybrid modeling

How industrial solvers and learning models can enrich each other ?

01



## AFS: Agility and fidelity of simulations

How to improve agility and fidelity of simulation in complex systems design?

02



## S2I: Industrial infrastructure supervision

How to improve decision-making on distributed industrial systems via machine learning techniques ?

03



## SAA: Augmented multi-agent simulation

How can multi-agent models benefit from real data and bring out atypical situations?

04



## SMD: Business Semantics for Multi-source Data Mining

How to link heterogeneous data with established practical knowledge?

05



## CAB: Cockpit and Bidirectional Assistant

How to develop a virtual assistant that learns from expert and learns to the expert

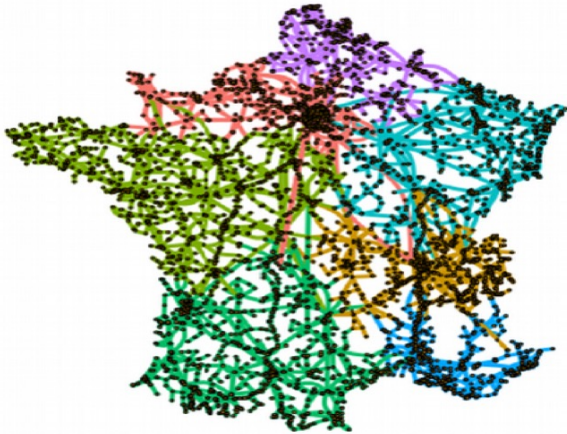
06



# Some physical problems in Industry

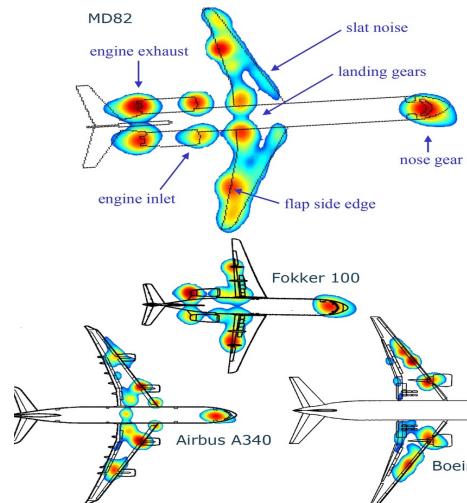
- Related to the desing and supervision of complex (physical) systems
- Covering various fields in physics (mechanics, fluid dynamics, aerodynamics, electromagnetism ...)
- In a wide variety of Applications in industry, in particular in numerical **simulation**

## Electricity (power grids)



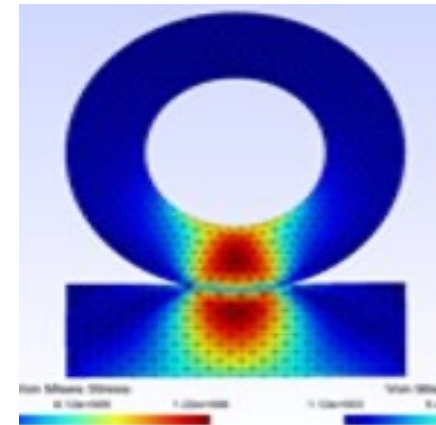
Picture from Marot, A., et al. (2018). Guided machine learning for power grid segmentation. In *2018 IEEE PES Innovative Smart Grid Technologies Conference Europe (ISGT-Europe)* (pp. 1-6).

## Aerodynamics



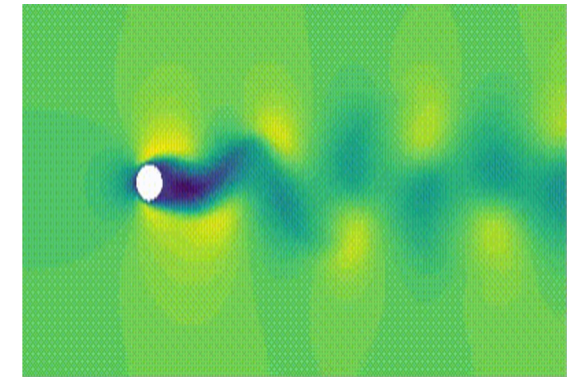
Merino-Martínez et al. *CEAS Aeronautical Journal* (2019).

## Solid Mechanics pneumatics



From the internet

## Fluid Flows/Dynamics



from Emmanuel Menier (PhD, LSIN/SystemX, 2024)

## Domain Challenges : Physical systems that are

- Complex to model/solve analytically
  - Computationally expensive to solve numerically
- eg. , Computational Fluid Dynamics – CFD, Turbulence, Flows

## Scientific Challenges

- Problems highly-nonlinear, high-dimensional, with complex structures (eg. organized in graphs...)
- Need for adapted NN architectures: Graph NNets, Deep AE ..

Hybrid modeling: combining ML and *Physics*

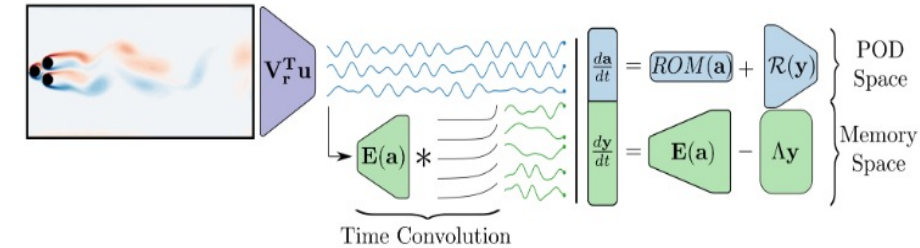
- ➔ Enables prior scientific knowledge based on physics to be taken into account in data-driven machine learning methods: e.g approaches include PINNs - Physics-Informed Neural Nets (Raissi's paper in 2019)
- ➔ Has been successfully and increasingly applied to solve a wide variety of linear and nonlinear problems in physics, covering various fields like mechanics, fluid dynamics, thermodynamics, electromagnetism ...

In engineering, it allows

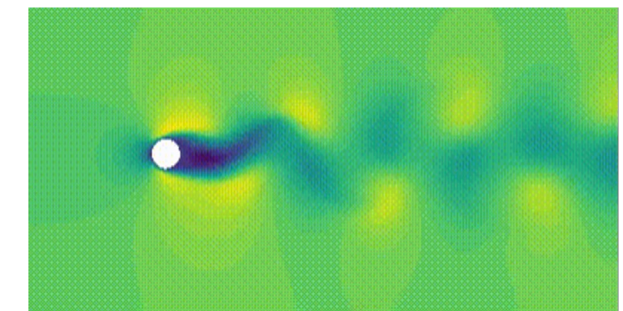
- ➔ the integration of analytical knowledge from physical laws governing the studied engineering systems
- to augment the statistical knowledge learned from observed/measured data (eg. Information extracted by deep learning from data)
- for reducing the high cost of physical simulation, in particular in the industrial sector

## Challenges and possible solutions (studied as part of the HSA project):

- Augmenting physical solvers with data-driven models that integrate physics constraints
  - Building model architecture adapted to the complex physical structures/systems
  - Reducing the simulation cost
- Hybrid Machine Learning as surrogate models for physical simulation, aiming to Replace physical solvers with
- Deep learning integrating physical constraints (eg. Deep Graph Nets for PDEs)
- Deal with high-dimensional, non-linear, and complex structures (e.g reduced modeling, ..)

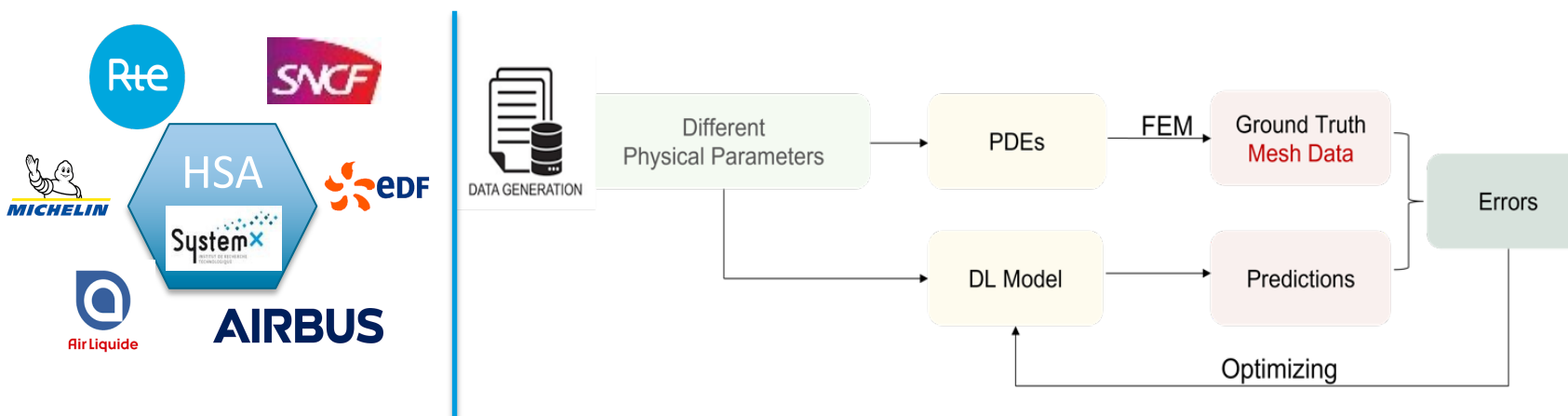


High-Dimensional non-linear Physical Equations



Reduced models and deep learning for PDEs  
PhD Thesis of E. Menier, 2024 (LISN, Inria/SystemX)

E. Menier et al., 2023. CD-ROM: Complementary Deep-Reduced Order Model. *Computer Methods in Applied Mechanics and Engineering* 410. [Read Online](#)



Deep Graph Neural Networks for Numerical Simulation of PDEs. PhD of W. Liu. 2023 (LISN, Inria/SystemX). [Read Online](#)



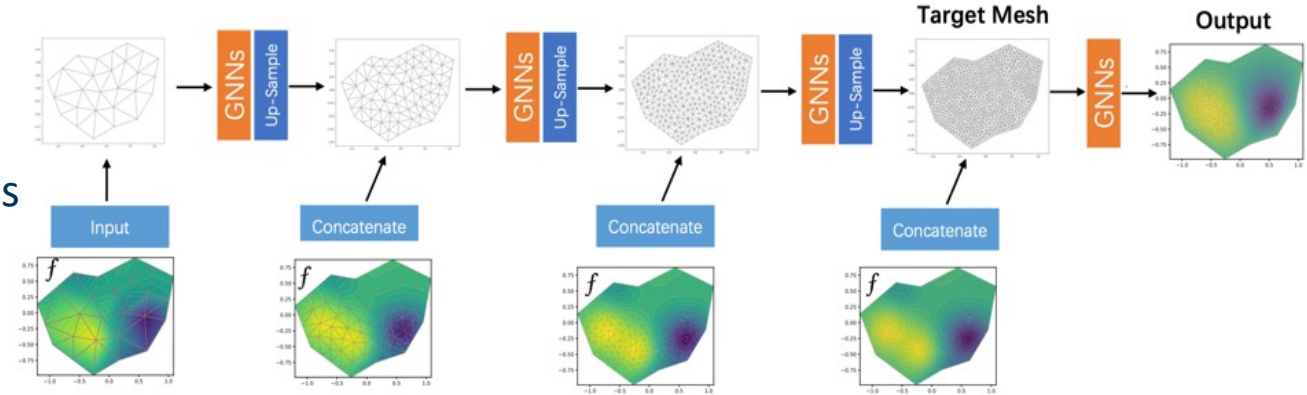
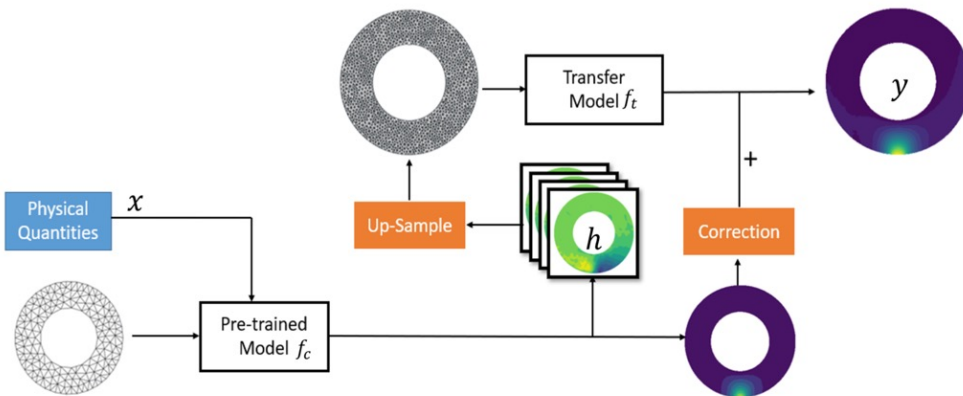
# Project HSA : simulation and deep learning of graphs

## Graph Neural Nets for 3D meshes

More suitable, as they operate by construction on graphs

- Generic nature of the learned models
- Transfer learning for improved results
- Prediction can be improved via transfer learning:

from low fidelity (coarse mesh) to high fidelity (finer mesh) models



## Wheel contact profile

Physics: contact equations

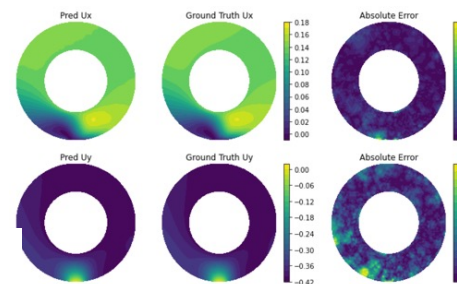
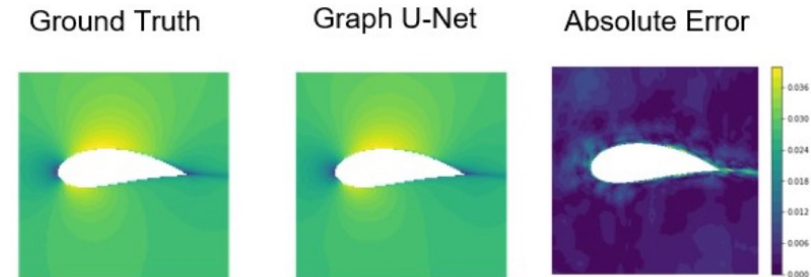


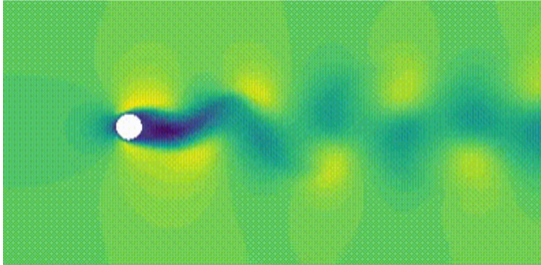
Figure 6.3: An example of wheel contact prediction

## Prediction of the airflow profile around an aircraft wing (Air Foil)

Physics: Navier-Stokes equations



# Dynamics: Hybrid ML for HD dynamical physical systems

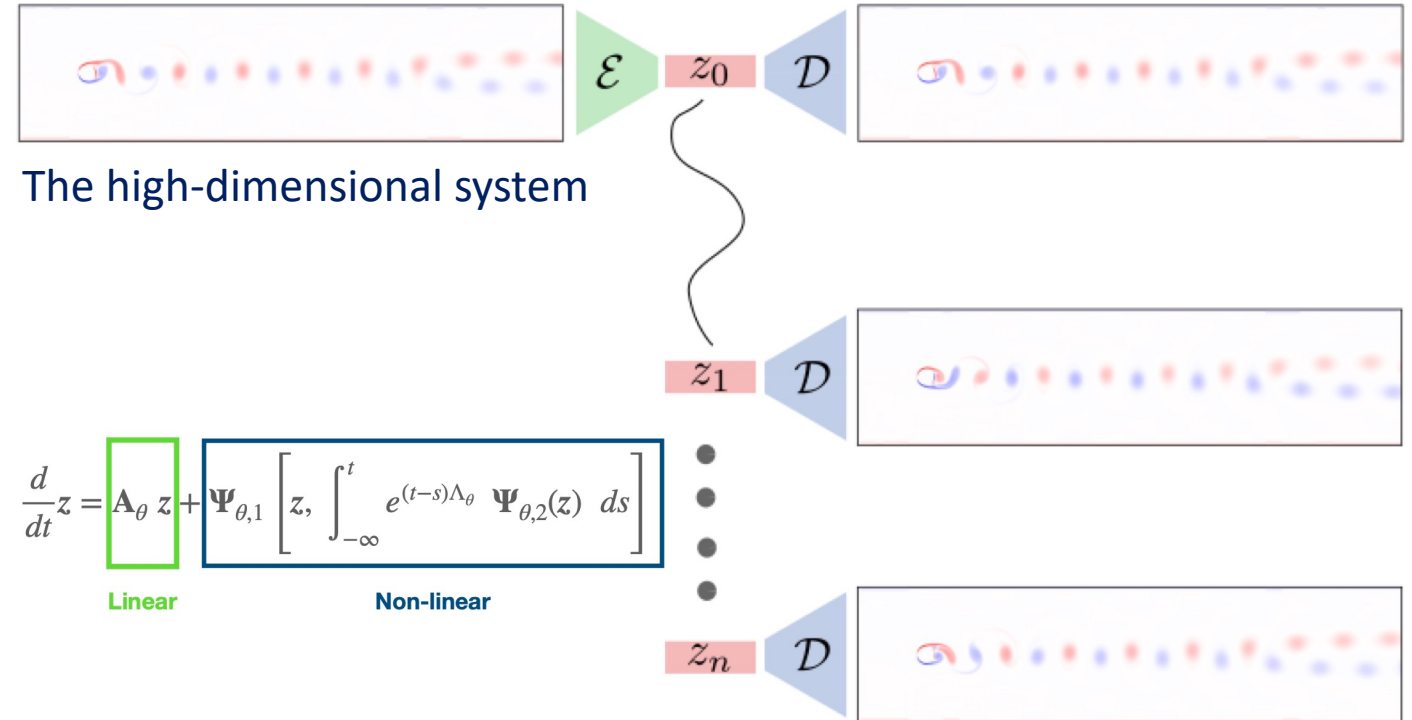


High-Dimensional non-linear Dynamical Systems:

## Goals:

Recover the dynamics, non-linearity in a high-dimensional setting

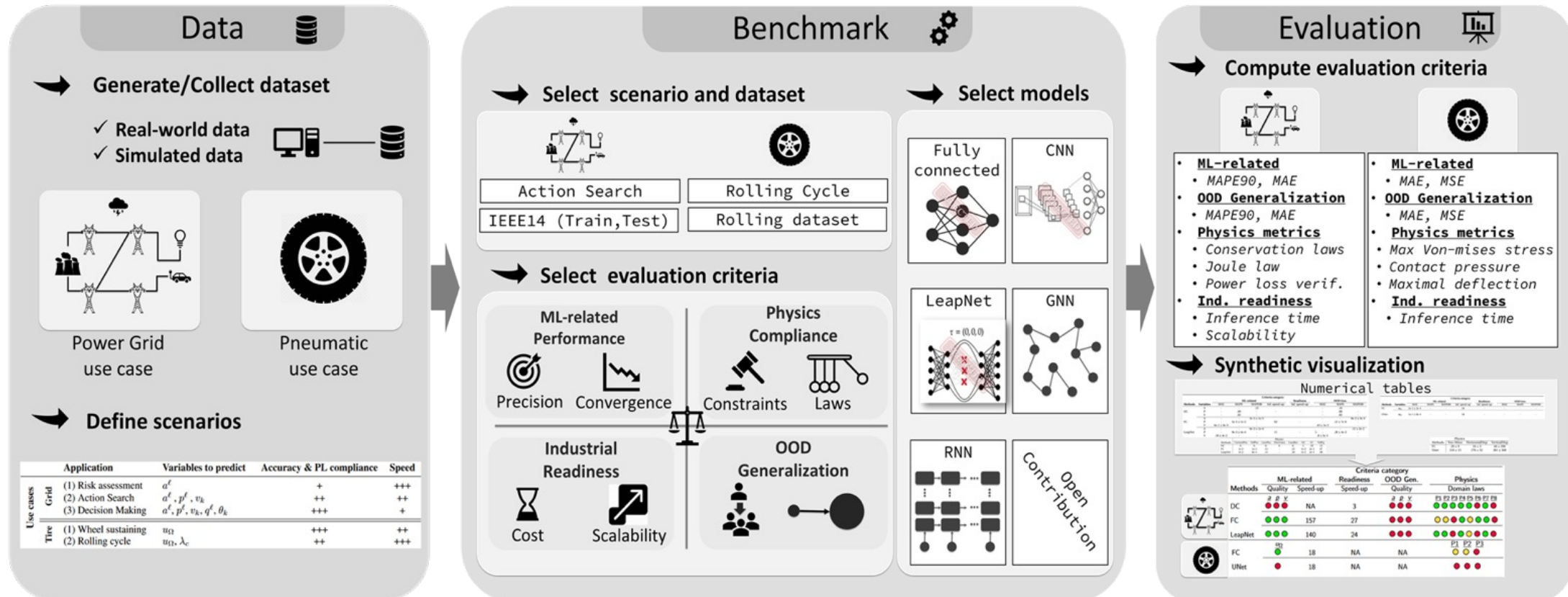
Interpretable learning of effective dynamics (ILED) architecture:



The lower-dimensional representation ( $\mathbf{z}$ ) is propagated in time using a linear and a non-linear part based on the Mori-Zwanzig formalism

# LIPS: Platform of validation of hybrid AI models

- **LIPS** : Learning Industrial Physical Simulation benchmark suite (*Result of the project HSA-IA2*)
- Evaluation of physical simulator augmented by machine learning
- Open-source Framework <https://github.com/IRT-SystemX/LIPS> Published at NeurIPS2022
- 1st framework for evaluating augmented physical simulators
- 7 use cases integrated

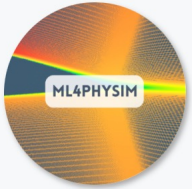




LIPS hosts the two following competitions:


<https://www.codabench.org/competitions/1534/> (Closed)

<https://www.codabench.org/competitions/2378/> **Running!**

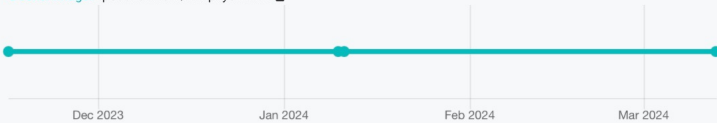


## MACHINE LEARNING FOR PHYSICAL SIMULATION CHALLENGE

128 PARTICIPANTS
1165 SUBMISSIONS


**€7000 to be shared by the 5 winners (see prizes page)**

ORGANIZED BY: Systemx  
CURRENT PHASE ENDS: Never  
CURRENT SERVER TIME: 8 Mai 2024 À 08:00 UTC+2  
Docker image: lipsbenchmark/ml4physim:1.4



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### New ML4PhySim challenge : The powergrid usecase

## Competition Overview

This competition aims at promoting the use of ML based surrogate models to solve physical problems, through a task addressing a recently published dataset called **AirFRANS** related to **airfoil design (CFD simulation)**.

The competition will address the challenge of improving baseline solutions of the Airfoils design use case by building ML-based surrogate models. The overall aim is to improve the tradeoff between the precision of obtained solutions and the related computational cost.


Baseline	ML-related (40%)		Criteria category				Score (100%)
			Application-based context (30%)		Physics (30%)		
	Accuracy	Speed-up	OOD Accuracy	Speed-up	Domain laws		
AirFRANS	$\bar{u}_x, \bar{u}_y, \bar{p}, \bar{v}_x, \bar{v}_y$	1000	$\bar{u}_x, \bar{u}_y, \bar{p}, \bar{v}_x, \bar{v}_y, C_D, C_L, \rho_D, \rho_L$	1000	$C_D, C_L, \rho_D, \rho_L$		55.87
GraphSAGE	●●●●●	●●●●●	●●●●●	●●●●●	●●●●●	●●●●●	44.57
FC	●●●●●	●●●●●	●●●●●	●●●●●	●●●●●	●●●●●	44.57
OpenFOAM	●●●●●	1	●●●●●	1	●●●●●	●●●●●	82.5



## MACHINE LEARNING FOR PHYSICAL SIMULATION CHALLENGE - POWERGRID USE CASE

31 PARTICIPANTS
0 SUBMISSIONS

ORGANIZED BY: Systemx  
CURRENT PHASE ENDS: 14 Mai 2024 À 02:00 UTC+2  
CURRENT SERVER TIME: 8 Mai 2024 À 08:04 UTC+2  
Docker image: codalab/codalab-legacy:py37



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## Prizes

**General prizes:**

- 1st Prize : 3000 €
- 2nd Prize : 2000 €
- 3rd Prize : 1000 €

**Special prizes:**

- Most accurate ML model (without speedup consideration) : 1000 €
- Best student solution : 1000 €

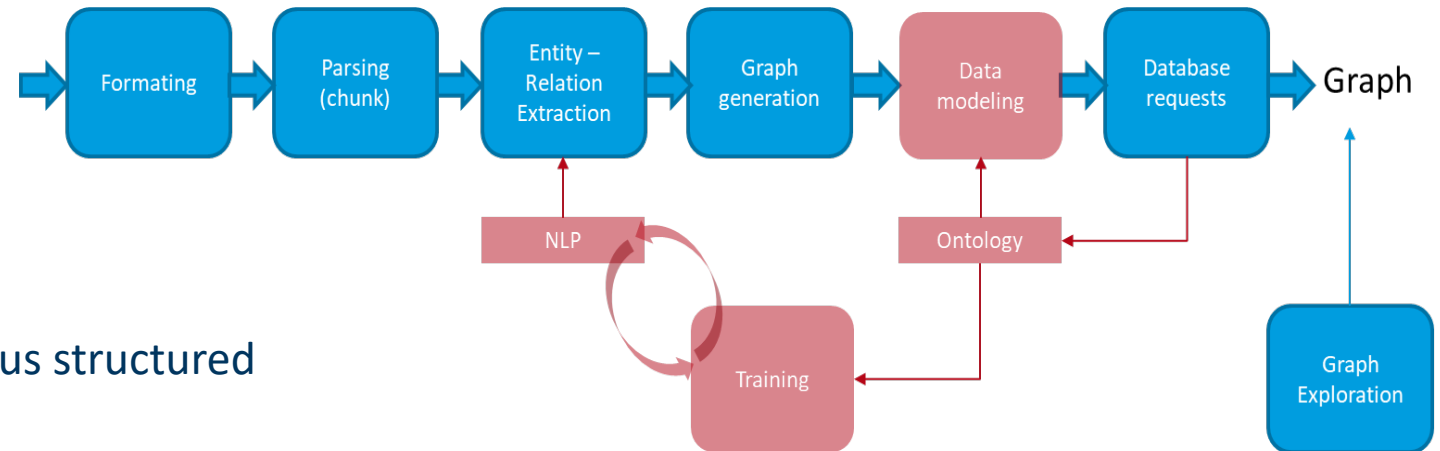
The general and special prizes are not cumulative. Winning one of the general prizes hinder the access to special prizes.

## Framework:

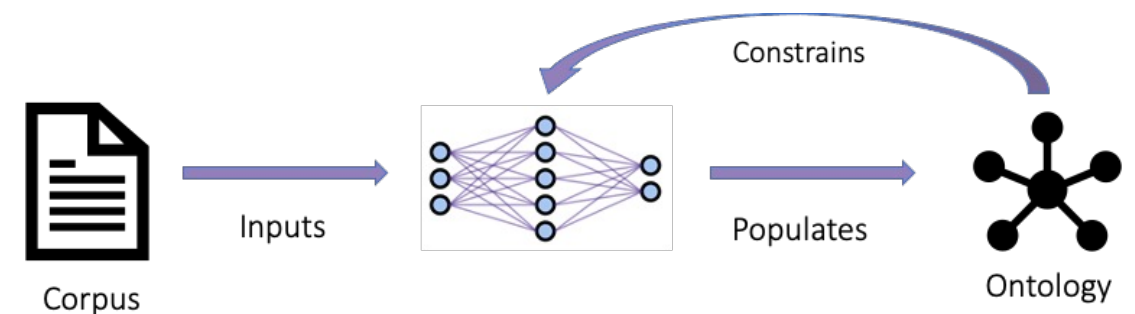
Building ML-based on knowledge graphs from expert/business language data

## Approach

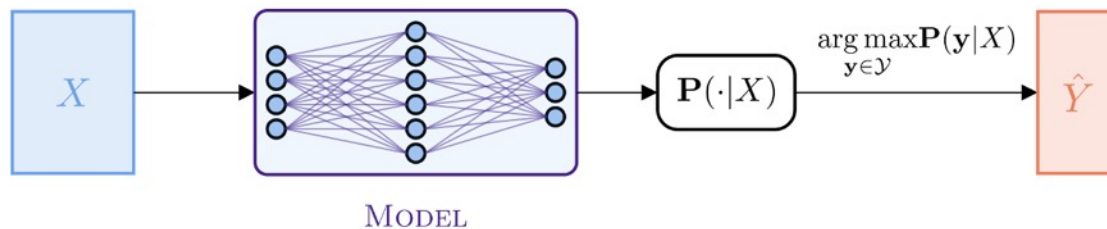
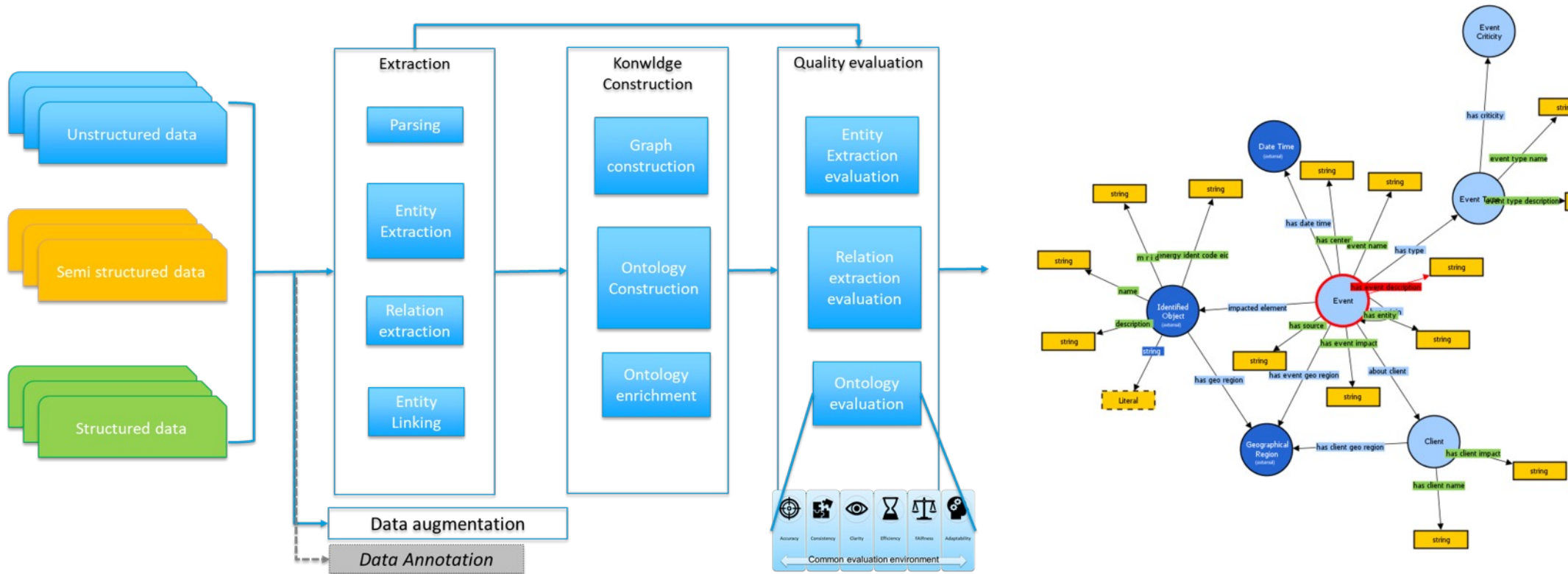
- Information extraction from heterogeneous structured and semi-structured text corpora...
- NLP approach; Semantic annotation
- Taking into account domain rules/constraints in the numerical-AI based decision



## Neuro-symbolic pipeline



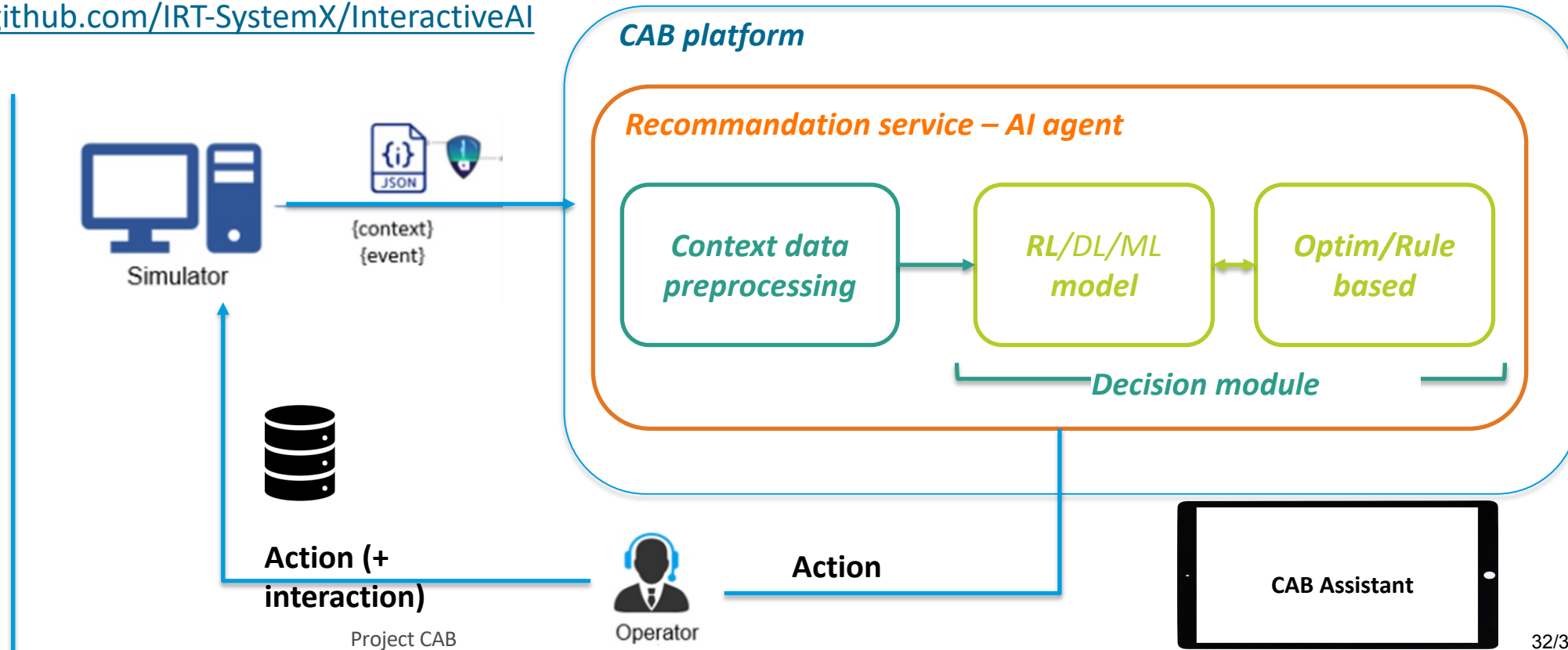
# Project SMD : Integrating Expert/Business semantics in ML



- => Insertion of logical rules at the inference step :
- Recalculer  $P(y|X, \alpha)$  in lieu of the learnt  $P(y|X)$
  - $\alpha$  is a rule encoding the validity of the prediction  $\hat{y}$

## Objectives and challenges

- Design and implement a Bidirectional Assistant to support operators in network supervision and aircraft piloting activities
- Bidirectional assistant: The assistant can learn from and to (inform) the operator
- **Platform:** <https://github.com/IRT-SystemX/InteractiveAI>



## Challenges and industrial applications in

- Hybrid AI: exploiter les connaissances métiers de natures physique et symbolique dans les modèles d'apprentissage
- **Trustworthy AI**: concevoir et industrialiser des systèmes à base d'intelligence artificielle de confiance

A French unique community to design and industrialise trustworthy AI-based critical systems

Multi-technology, multi-domain, multi-engineering

**AIRBUS**

**Air Liquide**

**Atos**

**NAVAL  
GROUP**

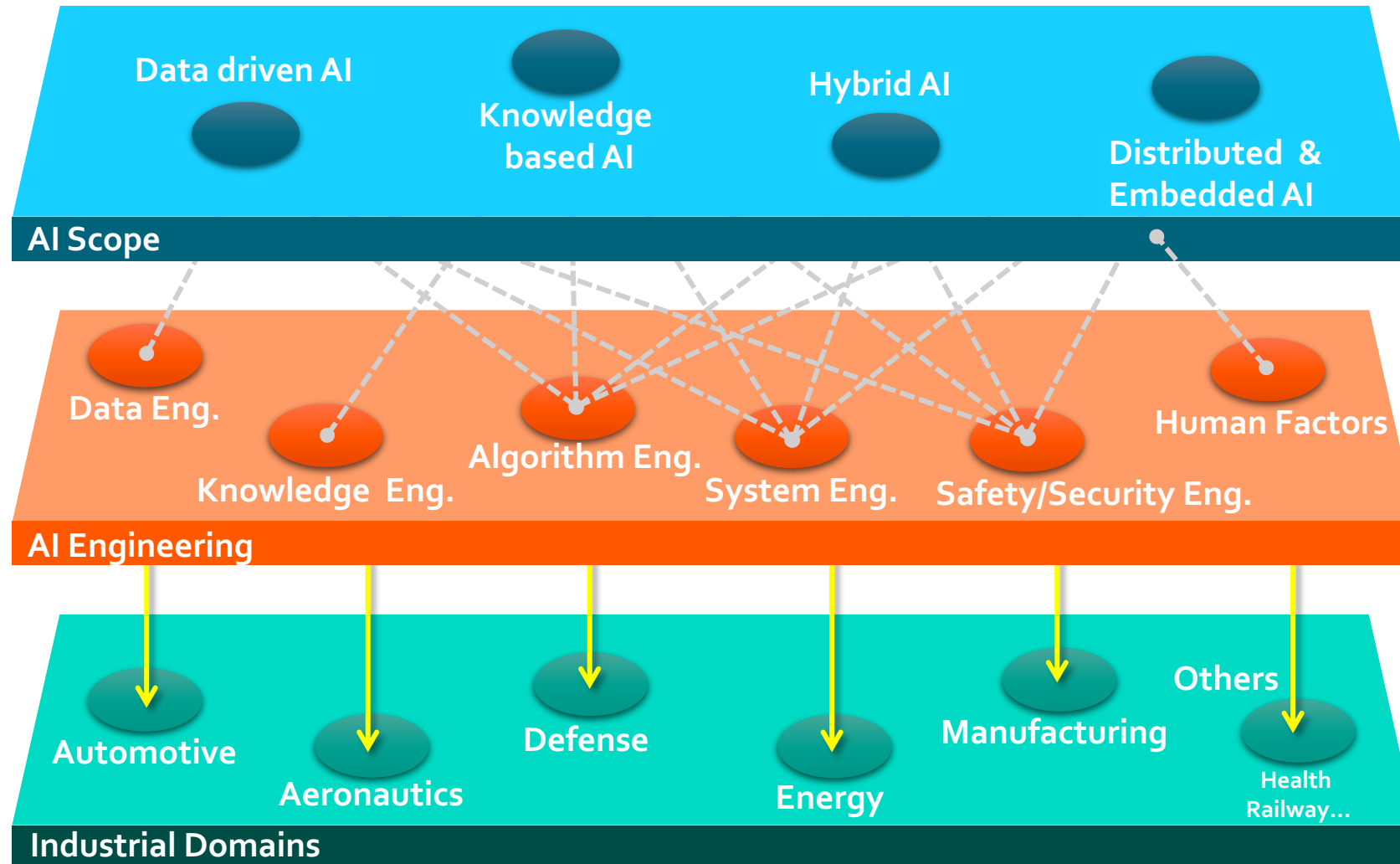
**RENAULT**

**SAFRAN**

**sopra steria**

**THALES**  
Building a future we can all trust

**Valeo**



**cea**

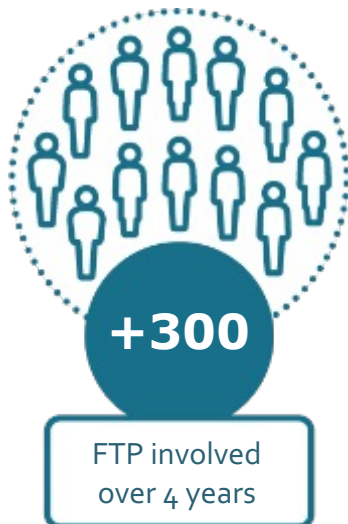
**cnrs**  
Département des Sciences

**Inria**

**IRT  
SAINT EXUPÉRY**

Systemx  
INSTITUT DE RECHERCHE  
TECHNOLOGIQUE





- **confiance.ai**: methods and tools for trusted AI ➔ High expectations for industry
- In parallel of development of tool chain, many scientific challenges remain, including:
- Ongoing PhD theses within confiance.ai :
  - PhD Theis of Adrien Le Coz: Data coverage and operational **domain design** ODD (Computer Vision)
  - PhD Thesis of Paul La Barbarie: **Robustness** to 'patch' adversarial attacks (Computer Vision)
  - PhD Thesis of Lucas Schott: **Reinforcement** learning and human in the loop
  - PhD Thesis of Gayane Taturyan: Statistical control of **Fairness**/Bias in Machine Learning (Stat)
  - PhD Theis of Housseem Ouertatani : **Optimized** hardware **deployment** (Neural Architecture Search)
  - PhD Thesis of Abdelmouaiz Tebjou: Conformal prediction (deployed) AI algorithms **monitoring**



THANK YOU FOR YOUR ATTENTION

